



# Product range overview

Function	Туре	Description
Drives	Rodless	
	DDLI	Without guide     With displacement encoder for contactless measurement     Based on linear drive DGC-K     Supply ports on end face     System product for handling and assembly technology
	DGCI	With guide     With displacement encoder for contactless measurement     Based on linear drive DGC     Supply ports optionally on end face or front     System product for handling and assembly technology
	With piston rod	
	DNCI	<ul> <li>With displacement encoder for contactless measurement</li> <li>Various piston rod variants</li> <li>Standards-based cylinder to ISO 15552</li> </ul>
	DDPC	With displacement encoder for contactless measurement     Various piston rod variants     Standards-based cylinder to ISO 15552
	DNC/DSBC	With attached potentiometer MLO-LWG     Various piston rod variants     Standards-based cylinder to ISO 15552
Swivel modu	le Swivel module	
		<ul> <li>Based on swivel module DSM</li> <li>Integrated rotary potentiometer</li> <li>Compact design</li> <li>Wide range of mounting options</li> </ul>

# Product range overview

Piston	Stroke/swivel angle	Suitable						
diameter		for positioning with	for end-position controller		for use as a measuring			
	[mm/°]	CPX-CMAX	CPX-CMPX	SPC11	cylinder			
Rodless								
25, 32, 40, 63	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000		•		•			
18, 25, 32, 40, 63	100, 160, 225, 300, 360, 450, 500, 600, 750, 850, 1000, 1250, 1500, 1750, 2000	•	•	•	•			
With piston rod								
32, 40, 50, 63	10 2000	-	-	-	•			
	100 750	•	•	•	-			
80, 100	10 2000	-	-	-	•			
	100 750	•	•		-			
32, 40, 50, 63, 80	100, 150, 225, 300, 360, 450, 600, 750	•	•	•	•			
Swivel module								
25, 40, 63	270							

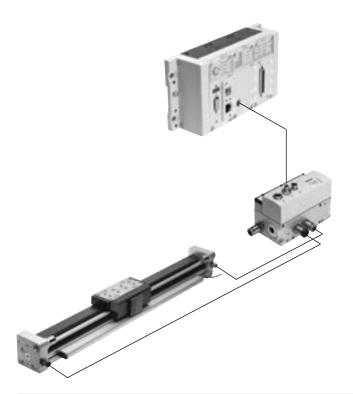
## Key features

### Servo-pneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks. The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate to the application, can be combined in almost any way on the CPX terminal.

#### Advantages:

- · Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alerts are all possible via TCP/IP
- Modules can be quickly exchanged and expanded without altering the wiring



#### Axis controller CPX-CMAX



### Free choice:

Position and force control, directly actuated or selected from one of 128 configurable position sets. If you are looking for something more: The configurable record sequencing function enables simple functional sequences to be realised with the axis controller CPX-CMAX.

Everything is recognisable: the auto-identification function identifies each participant with its device data on the controller CPX-CMAX.

### Also included:

Actuation of a brake or clamping unit via the proportional directional control valve VPWP is also part of the scope of performance of the controller CPX-CMAX.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other.

Commissioning via FCT (Festo configuration software) or via fieldbus: no programming, only configuration.

### Advantages:

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment

# Key features

## End-position controller CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit.

Improved standstill control.

Actuation of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX.

The 5/3-way proportional directional

control valve for applications with Soft

pressure sensors, with new diagnostic

Stop and pneumatic positioning.

Fully digitalised - with integrated

Flow rates of 350, 700, 1400 and

functions.

In sizes 4, 6, 8 and 10.

measuring sensors.

Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal. All system data can be read and written via the fieldbus, including, for example, the mid-positions. Data sheets → Internet: cpx-cmpx Advantages:

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
  - Up to 30% faster cycle ratesSignificantly reduced system
- vibration
  Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time of the machine

Data sheets  $\rightarrow$  Internet: vpwp

### Proportional directional control valve VPWP



### Measuring module CPX-CMIX



2000 l/min. Fully digital data acquisition and transmission means that pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital

Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or alternatively for a potentiometer of the type MLO.

With switching output for controlling a

Colour-coded supply ports.

Pre-assembled cables guarantee

faultless and fast connection with the

controllers CPX-CMPX and CPX-CMAX.

brake.

### Advantages:

- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for controlling a brake/clamping unit

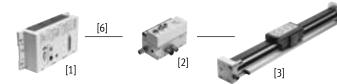
### Data sheets $\rightarrow$ Internet: cpx-cmix

Advantages:

- All process steps can be documented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on

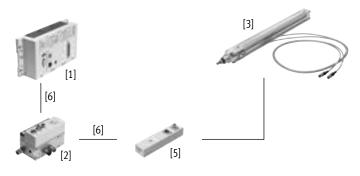
# Drive options

### System with linear drive DDLI, DGCI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Linear drive DDLI, DGCI with displacement encoder
- [6] Connecting cable KVI-CP-3-...

### System with standards-based cylinder DNCI, DDPC



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Standards-based cylinder DNCI, DDPC with displacement encoder
- [5] Sensor interface CASM-S-D3-R7
- [6] Connecting cable KVI-CP-3-...

- Pneumatic rodless linear drive with displacement encoder, with or without recirculating ball bearing guide
- Displacement encoder with absolute and contactless measurement
- Diameter:
  - With DGCI: 18 ... 63 mm
  - With DDLI: 25 ... 63 mm
- Stroke: 100 ... 2000 mm in fixed lengths
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 1 ... 180 kg
- No sensor interface required

### Data sheets → Internet: dnci

### Advantages:

Advantages:

CPX-CMAX)

• Complete drive unit

- Compact drive unit
- Can be used universally
- Also with guide unit
- For fast and accurate positioning up to ±0.5 mm (only with axis controller CPX-CMAX)
- integrated displacement encoder, conforms to DIN ISO 6432, VDMA 24 562, NF E 49 003.1 and Uni 10 290

· Standards-based cylinder with

- Displacement encoder with contactless and incremental measuring
- Diameter: 32 ... 100 mm
- Stroke: 100 ... 750 mm
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 3 ... 450 kg and the corresponding sensor interface CASM-S-D3-R7
- Pre-assembled cables guarantee faultless and fast electrical connection

# Data sheets $\rightarrow$ Internet: ddli or dgci

• DDLI for easy connection to the

• Excellent running characteristics

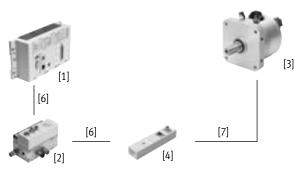
• For fast and accurate positioning up

to ±0.2 mm (only with axis controller

customer's guide system

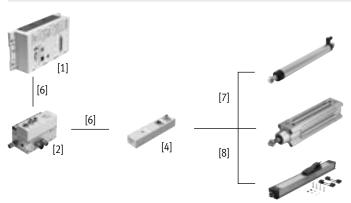
# Drive options

## System with swivel module DSMI



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [3] Swivel module DSMI with displacement encoder
- [4] Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- [7] Connecting cable NEBC-P1W4-K-0.3-N-M12G5

## System with potentiometer



- [1] Controller module CPX-CMPX or CPX-CMAX
- [2] Proportional directional control valve VPWP
- [4] Sensor interface CASM-S-D2-R3
- [6] Connecting cable KVI-CP-3-...
- [7] Connecting cable NEBC-P1W4-K-0.3-N-M12G5
- [8] Connecting cable NEBC-A1W3-K-0.4-N-M12G5

- Swivel module DSMI with integrated displacement encoder
- Identical design to pneumatic swivel module DSM
- Absolute displacement encoder based on a potentiometer
- Swivel range from 0 ... 270°
- Size: 25, 40, 63
- Max. torque: 5 ... 40 Nm
  Range of applications: Soft Stop and pneumatic positioning
- Mass moments of inertia of 15 ... 6000 kgcm<sup>2</sup> and the corresponding sensor interface CASM-S-D2-R3
- Pre-assembled cables guarantee faultless and fast connection to the proportional directional control valve VPWP
- Attachable potentiometers with absolute measurement, with high degree of protection
- With connecting rod or moment compensator
- Measuring range: Connecting rod: 100 ... 750 mm Moment compensator: 225 ... 2000 mm
- Pre-assembled cables guarantee faultless and fast connection with the sensor interface CASM
- Range of applications: Soft Stop and pneumatic positioning with cylinder diameters of 25 ... 80 mm
- Loads from 1 ... 300 kg

## Data sheets $\rightarrow$ Internet: dsmi

## Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- With adjustable fixed stops
- For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

## Data sheets $\rightarrow$ Internet: casm

### Advantages:

- Easy installation and fast commissioning
- Cost-effective
- Can also be used in harsh ambient conditions
- Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder

# Drive options

## System components for Soft Stop systems with end-position controller CPX-CMPX

	Linear drive	Standards-based cylinder	Swivel module	Displacement encode	er	→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
End-position controller	•					стрх
CPX-CMPX						
Proportional directional control valve						vpwp
VPWP						
Sensor interface	-	-	•	•	-	casm
CASM-S-D2-R3						
Sensor interface	-		-	-	-	casm
CASM-S-D3-R7						
Connecting cable						kvi
KVI-CP-3						
Connecting cable	-	-		■/-	-	nebc
NEBC-P1W4						
Connecting cable	-	-	-	- / =	-	nebc
NEBC-A1W3				,		
Connecting cable	-	-	-	-		vpwp
NEBP-M16W6						

### System components for pneumatic positioning systems with axis controller CPX-CMAX

	Linear drive	Standards-based cylinder	Swivel module	Displacement encode	er	→ Page/ Internet	
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS		
Axis controller CPX-CMAX			•	•	•	cmax	
Proportional directional control valve VPWP	•		•			vpwp	
Sensor interface CASM-S-D2-R3	-	-			-	casm	
Sensor interface CASM-S-D3-R7	-		-	-	-	casm	
Connecting cable KVI-CP-3	•					kvi	
Connecting cable NEBC-P1W4	-	-		■ / -	-	nebc	
Connecting cable NEBC-A1W3	-	-	-	- / ■	-	nebc	
Connecting cable NEBP-M16W6	-	-	-	_		vpwp	

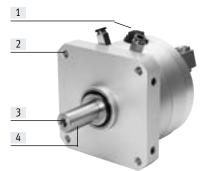
### System components for measuring cylinders with measuring module CPX-CMIX

	Linear drive	Standards-based cylinder	Swivel module	Displacement encode		→ Page/ Internet
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	
Measuring module CPX-CMIX-M1-1	•	•				cmix
Sensor interface CASM-S-D2-R3	-	-	•		-	casm
Sensor interface CASM-S-D3-R7	-	•	-	-	-	casm
Connecting cable KVI-CP-3	(■) <sup>1)</sup>	•	•		(■)	kvi
Connecting cable NEBC-P1W4	-	-		■ / -	-	nebc
Connecting cable NEBC-A1W3	-	-	-	- / ■	-	nebc
Connecting cable NEBP-M16W6	-	-	-	-		vpwp

1) As an extension

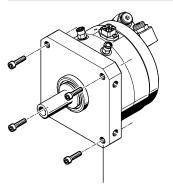
# Key features

## At a glance

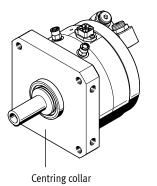


- [1] Connector plug for displacement encoder
- [2] Wide range of integrated mounting options
- [3] Option for mounting on the drive shaft by the customer
- [4] Featherkey
- [5] Fixed stop with precision adjustment of the swivel angle
- [6] Sensor bracket for mounting proximity switch, for contactless position sensing

Mounting options

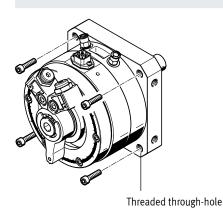


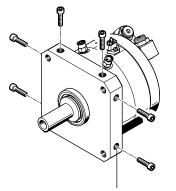
Threaded through-hole





- [7] Fixed stop can be set at any point within the swivel angle
- [8] Manual operation via internal hexagon socket in the drive shaft. A female thread is already integrated for attachment of an additional drive shaft by the customer.



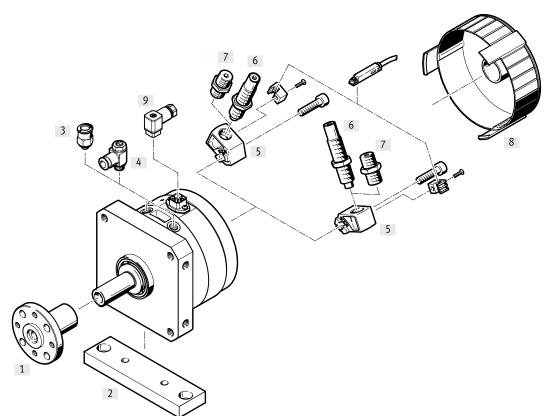


Basic thread

# Type codes

001	Series		003	Nominal swivel angle [°]
DSMI	Semi-rotary drive with displacement encoder, double-acting		270	270
002	Size	I	004	Position sensing
25	25		A	For proximity sensor
40	40			
63	63		005	Variant
			В	B-series

# Peripherals overview



I	Accessories
I	///////////////////////////////////////

		For size	Description	→ Page/Internet
[1]	Push-on flange FWSR	25,40	For mounting attachments	17
[2]	Mounting plate HSM	25,40	Adapter plate for mounting the drive	17
[3]	Push-in fitting QS	25, 40, 63	For connecting tubing with standard O.D. (push-in fittings are included in the scope of delivery of the drive)	qs
[4]	One-way flow control valve GRLA	25, 40, 63	For regulating speed (is recommended when using the DSMI as a measuring cylinder)	19
[5]	Cushioning mount DSM-B	25, 40, 63	<ul> <li>For elastic cushioning elements</li> <li>For shock absorbers</li> <li>As a mechanical stop in Soft Stop applications</li> </ul>	18
[6]	Shock absorber DYSC	25, 40, 63	Self-adjusting shock absorbers with fixed stop (is recommended when using the DSMI as a measuring cylinder)	18
[7]	Cushioning kit DSMP-B	25, 40, 63	Elastic cushioning elements with fixed stop	18
8]	Cover cap AKM	25,40	Reduces the risk of injury in the swivel range of the stop lever	18
9]	Plug socket SD	25, 40, 63	For connecting the displacement encoder	19

# Data sheet





### General technical data

Size		25	40	63			
Design		Vane	Vane				
	Drive shaft, fitted with ball b	earings					
Mode of operation	Double-acting						
Type of mounting	Via female thread						
Position sensing		Via integrated angular displa	acement encoder				
		Via proximity sensor <sup>1)</sup>					
Measuring principle (angular displacement encoder)		Analogue with conductive plastic potentiometer					
Min. travel speed	[°/s]	50					
Max. travel speed	[°/s]	2,000					
Max. swivel angle <sup>2)</sup>	[°]	272					
Setting range of swivel angle	[°]	0 270					
Pneumatic connection		M5	G1/8	G1/4			
Push-in fitting used		QSM-M5-6	QS-G1/8-8-I	QS-G1/4-8-I			
Compressed air tubing O.D.	[mm]	6	8	8			

1) Not included in the scope of delivery, can be ordered as an option

2) Note stroke reduction in combination with axis controller CPX-CMAX

#### Operating and environmental conditions

-		
Operating pressure	[bar]	210
Operating pressure <sup>1)</sup>	[bar]	48
Operating medium <sup>2)</sup>		Compressed air to ISO 8573-1:2010 [6:4:4]
Note on the operating/pilot medium		Operation with lubricated medium not possible
		Pressure dew point 10°C below ambient/medium temperature
Ambient temperature <sup>3)</sup>	[°C]	-10+60
Vibration resistance to DIN/IEC 68, Part 2-6		Severity level 2
Continuous shock resistance to DIN/IEC 68, Part 2-82		Severity level 2
CE marking (see declaration of conformity) <sup>4)</sup>		To EU EMC Directive
Corrosion resistance class CRC <sup>5)</sup>		1

1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX

2) The proportional directional control valve VPWP, MPYE used requires these characteristic values

3) Note operating range of proximity switches

4) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary. 5) Corrosion resistance class CRC 1 to Festo standard FN 940070

Low corrosion stress. Dry indoor application or transport and storage protection. Also applies to parts behind coverings, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).

## Weight

Size		25	40	63
DSMI	[g]	1080	3950	6900

# Data sheet

Torque [Nm]								
Size	25	40	63					
Torque <sup>1)</sup>	5	20	40					

1) Theoretical values, calculated at 6 bar

#### Permissible forces on the drive shaft

Size		25	40	63
Max. radial force	[N]	120	350	500
Max. axial force	[N]	50	120	500
Max. swivel frequency <sup>1)</sup>	[Hz]	2		1

1) At max. permissible mass moment of inertia, operating pressure of 6 bar and a swivel angle of  $270^{\circ}$ 

## - 📲 - Note

Further technical data

→ Internet: dsm

### Positioning characteristics with axis controller CPX-CMAX

Size		25	40	63					
Mounting position		Any	Any						
Resolution	[°]	0.1							
Repetition accuracy	[°]	≤ ±0.3							
Min. mass moment of inertia, horizontal <sup>1)</sup>	[kgm <sup>2</sup> ]	15 x 10 <sup>-4</sup>	60 x 10 <sup>-4</sup>	300 x 10 <sup>-4</sup>					
Max. mass moment of inertia, horizontal <sup>1)</sup>	[kgm <sup>2</sup> ]	300 x 10 <sup>-4</sup>	1200 x 10 <sup>-4</sup>	6000 x 10 <sup>-4</sup>					
Min. mass moment of inertia, vertical <sup>2)</sup>	[kgm <sup>2</sup> ]	15 x 10 <sup>-4</sup>	60 x 10 <sup>-4</sup>	300 x 10 <sup>-4</sup>					
Max. mass moment of inertia, vertical <sup>2)</sup>	[kgm <sup>2</sup> ]	300 x 10 <sup>-4</sup>	1200 x 10 <sup>-4</sup>	6000 x 10 <sup>-4</sup>					
Min. travel speed	[°/s]	50	·						
Max. travel speed	[°/s]	2000							
Typ. positioning time, long stroke <sup>3)</sup>	[s]	0.35/0.60	0.30/0.55	0.64/1					
Typ. positioning time, short stroke <sup>4)</sup>	[s]	0.15/0.25	0.25/0.25	0.30/0.35					
Min. positioning stroke	[°]	5							
Max. swivel stroke <sup>5)</sup>	[°]	260							
Recommended proportional directional control valve	e								
For CPX-CMAX		VPWP-4-L-5-Q6-10-E-F	VPWP-4-L-5-Q8-10-E-F						

1) Must not change during the movement, but may be outside the centre of gravity

2) Must not change during the movement, must act at the centre of gravity

3) At 6 bar, vertical mounting position,  $260^\circ$  positioning angle at min./max. mass moment of inertia

4) At 6 bar, vertical mounting position,  $15^{\rm o}$  positioning angle at min./max. mass moment of inertia

5) A stroke reduction of 5° on both sides must be observed

# Data sheet

# Positioning characteristics with Soft Stop end-position controller CPX-CMPX, SPC11

Size		25	40	63
Mounting position		Horizontal		
End-position repetition accuracy <sup>1)</sup>	[°]	< ±0.2		
Intermediate-position repetition accuracy	[°]	±2		
Cushioning <sup>2)</sup>		Electronically controlled		
Min. mass moment of inertia, horizontal <sup>3)</sup>	[kgm <sup>2</sup> ]	15 x 10 <sup>-4</sup>	60 x 10 <sup>-4</sup>	300 x 10 <sup>-4</sup>
Max. mass moment of inertia, horizontal <sup>3)</sup>	[kgm <sup>2</sup> ]	300 x 10 <sup>-4</sup>	1200 x 10 <sup>-4</sup>	6000 x 10 <sup>-4</sup>
Min. swivel stroke	[°]	15		
Recommended proportional directional control valve				
For CPX-CMPX		VPWP-4-L-5-Q6-10-E-F	VPWP-4-L-5-Q8-10-E-F	
For SPC11		MPYE-5-M5-010-B	MPYE-5-1/8-LF-010-B	

1) When using the DSMI stops

2) The cushioning pad on the stop lever must be removed for applications with Soft Stop. The stop lever must not swivel to the end stop at too great a speed as this could damage the swivel module

3) Must not change during the movement, but may be outside the centre of gravity

#### Electrical data – Displacement encoder

Output signal			Analogue
Linearity error <sup>1)</sup>		[%]	<±0.25
Power supply <sup>2)</sup>		[V DC]	10
Max. current consumption		[mA]	4
Wiper current	Recommended	[µA]	<1
	Maximum <sup>3)</sup>	[mA]	10
Connection resistance		[kΩ]	5
Connection resistance tolerance		[%]	±20
Degree of protection			IP65
CE marking (see declaration of conformity	)		To EU EMC Directive <sup>4)</sup>
Electrical connection			4-pin plug, 🗆 16, DIN 45 322

1) In relation to max. swivel angle

2) Stabilised power supply is recommended, max. 42 V DC permissible

3) Only permissible in the short term in the event of a fault

4) For information about the area of use, see the EC declaration of conformity at: www.festo.com/sp → Certificates.

If the devices are subject to usage restrictions in residential, commercial or light-industrial environments, further measures for the reduction of the emitted interference may be necessary.

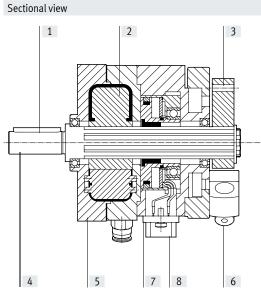
### Pin allocation for plug

3	1
2	4

Pin	Functio	n
1	24 V	Power supply
2	Sig	Signal
3	0 V	GND
4	PE	Shield

# Data sheet

# Materials

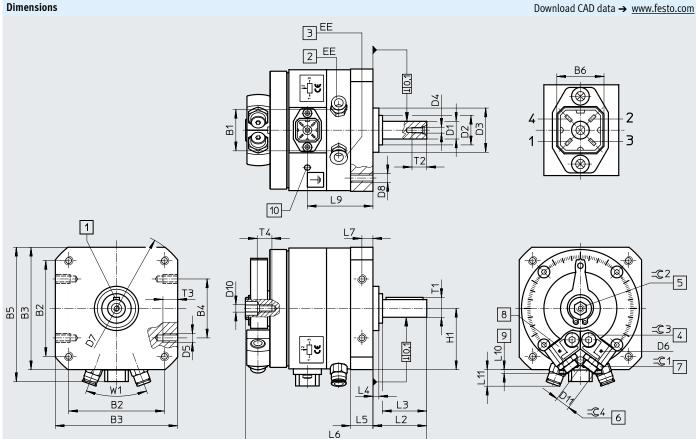


Cylinder/displacement encoder

cyano								
Cylind	Cylinder							
[1]	Featherkey	Steel						
[2]	Vane	Glass fibre-reinforced plastic						
[3]	Stop lever	Anodised wrought aluminium alloy						
[4]	Drive shaft	Nickel-plated steel						
[5]	Housing	Anodised wrought aluminium alloy						
[6]	Fixed stop/screw	Steel						
	Note on materials	Free of copper and PTFE						
		RoHS-compliant						
Displa	acement encoder							
[7]	Coupling	Polyurethane						
[8]	Housing	Anodised aluminium						

# Data sheet

# Dimensions



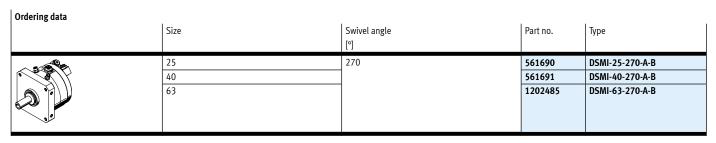
## [1] Featherkey position at 0°

- Blue release ring for supply port [2]
- [3] Black release ring for supply port
- [4] Locking screw for clamping the stop
- [5] Manual override (internal hexagon)

- End-position adjustment [6]
- Lock nut for end-position adjustment [7]
- [8] Infinitely adjustable stops
- [9] Projection for end-position adjustment
- [10] Earth terminal for self-tapping M4x8 screw

Size	B1	B2	B3	B4	B5	B6	D1		02	D3	D4	D5	D6	D7
[mm]	.0.5						g7		a	f8				a
[mm]	±0.5						Ø	5	Ø	Ø				Ø
25	28	65±0.3	83±0.3	40±0.2	91	16	12	20-	-0.3	30	M4	M6	M2	106±0.3
40	43.8	105±0.3	130±0.5	80±0.3	139	16	20	36-	-0.4	52	M6	M10	M2	168±0.5
63	55	125±0.5	152±0.5	80±0.3	157	16	25	40:	±0.3	70	M10	M10	M3	200±0.5
Size	D8	D10	D11	EE	H1	L2	L3	L	.4	L5	L6	L7	L9	L10
[mm]					±0.2	+0.6/-0.7	±0.2	±(	).4	+0.2/-0.3	6	±0.2	±1	
25	M6	M5	M10x1	M5	41.5	36.5	30		4	15.2	123±0.	5 7.5	44.5	2.9
40	M10	M6	M16x1	G1/8	65	62	50		8	23.7	184±0.	5 12	64.5	3.4
63	M12	M6	M22x1.5	G1/4	76	75.5	60	10	).5	28.5	235±0.	5 14	80.5	6
Size	L11	T1	T2	T3	T4	w	1	=© 1	=	-C 2	=© 3	<b>=</b> © 4	Feath	
[mm]	±2	max.	+2	±0.2									DIN 6	6885
25	12	13.5	10	10	10	40	)°	13		8	4	3	A4x4	x25
40	16	22.5	16	15	10	4(	)°	19		10	8	5	A6x6	5x45
63	20	28	22	16	20	4(	)°	27		10	8	5	A8x7	′x50

# Accessories

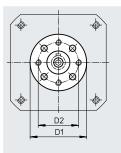


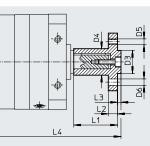
### Accessories

### Push-on flange FWSR

Material: Anodised aluminium Free of copper and PTFE







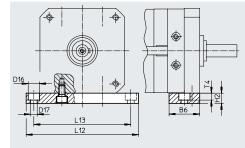
### Dimensions and ordering data

Dimensions and of	acting aut	~											
For size	B5	D11	D12	D13	D14	D15	L9	L10	L11	L12	Weight	Part no.	Туре
			ø	Ø	ø	ø							
[mm]			H13	g7							[g]		
25	35	M5	5.5	20	50	23	38	8	3	116.5	68	13240	FWSR-25
40	54	M8	9	36	70	38	60	11	5	186.5	240	14656	FWSR-40

### Mounting plate HSM

Material: Anodised aluminium Free of copper and PTFE





#### Dimensions and ordering data

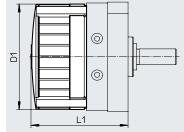
For size	B6	D16	D17	H2	L12	L13	T4	Weight	Part no.	Туре
		Ø	Ø							
[mm]								g		
25	30	11	6.6	10	110	95	6.8	94	165573	HSM-25
40	45	18	11	20	180	155	11	459	165575	HSM-40

# Accessories

Cover cap A	١KM
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Material: Polyamide





## Dimensions and ordering data

	5			
For size	D1	L1	Part no.	Туре
[mm]	Ø			
25	83	98.5±1.2	549196	AKM-25
40	130	135.5±1.5	549198	AKM-40

# Ordering data

	For size	Description	Part no.	Туре	PU <sup>1</sup>
Cushioning mount				-	
<u>ک</u>	25	For elastic cushioning elements	547902	DSM-25-B	2
	40	For shock absorbers	547904	DSM-40-B	
	63		552085	DSM-63-B	
Cushioning kit					
AND I	25	For cushioning mount DSMIB	550658	DSM-16/25-P-B	2
	40		550660	DSM-40-P-B	
O CONTRACTOR	63		552086	DSM-63-P-B	
Shock absorber					
$\sim$	25	For cushioning mount DSMIB	548012	DYSC-7-5-Y1F	1
A THUR	40		548014	DYSC-12-12-Y1F	
	63		553593	DYSC-16-18-Y1F	

1) Packaging unit

# Accessories

Ordering data – One-way flow	control valves					Data sheets → Internet: g
	For size	Connection		Material	Part no.	Туре
		Thread	For tubing O.D.			
or exhaust air						
ίΩ)	25	M5	3	Metal design	193137	GRLA-M5-QS-3-D
			4		193138	GRLA-M5-QS-4-D
			6		193139	GRLA-M5-QS-6-D
	40	G1/8	3		193142	GRLA-1/8-QS-3-D
			4		193143	GRLA-1/8-QS-4-D
			6		193144	GRLA-1/8-QS-6-D
			8		193145	GRLA-1/8-QS-8-D
	63	G1/4	10		193148	GRLA-1/4-QS-10-D
)rdering data – Connecting ca	hle					
Juering data – connecting ta	Description				Part no.	Туре
	Between sens	or interface CASM ar	d displacement encoder	549293	NEBC-P1W4-K-0.3-N-M12G5	

Ordering data – Plug sockets								
	Description	Part no.	Туре					
	For displacement encoder connection	194332	SD-4-WD-7					